

# How to get started hacking NetBSD

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[https://www.NetBSD.org/gallery/presentations/  
riastradh/eurobsdcon2023/getstarted.pdf](https://www.NetBSD.org/gallery/presentations/riastradh/eurobsdcon2023/getstarted.pdf)



# How to get started hacking NetBSD

```
cvs -d anoncvs@anoncvs.NetBSD.org:/cvsroot co -P src
```

```
# Alternatively, with Git or Mercurial:
```

```
# git clone https://github.com/NetBSD/src
```

```
# hg clone https://anonhg.NetBSD.org/src
```

```
cd src
```

```
./build.sh -O ../obj -U -u -m alpha -N1 -j4 release
```

# How I got started hacking NetBSD

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- ▶ Shopped around for something better
- ▶ ...something that would respect my autonomy
- ▶ ...and would run on my PowerBook G4

*Port-macppc archive*

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## NetBSD on a PowerBook G4

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- To: [port-macppc%NetBSD.org@localhost](mailto:port-macppc%NetBSD.org@localhost)
  - Subject: NetBSD on a PowerBook G4
  - From: Taylor R Campbell <[campbell@mumble.net](mailto:campbell@mumble.net)@localhost>
  - Date: Thu, 5 Jun 2008 18:15:34 -0400
- 

Hello! Last night I installed NetBSD 4.0 on my PowerBook G4 1 GHz, 12-inch, and, despite the apparent complexity of the installation instructions, once I understood how to follow only one thread through the instructions for six different installation media and three different major Open Firmware versions, the installation went pleasantly smoothly. Thanks!

I'd like to be able to experiment with this laptop as a primary work machine. There are two show-stopping issues with this proposition that a preliminary Googling answered with disappointing results, though, as did the INSTALL file for the 4.0 distribution. This PowerBook has an AirPort Extreme card, which is listed as unsupported; and if I am to use this for general-purpose work, support for sleep would be very convenient, but appears to be absent. Is there work in progress in it, and is this likely to change soon? Supposing that you were to stumble upon someone with a great deal of free time and interest in making it change soon, what would the changes entail?

NetBSD-Users archive

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## aligning control message ancillary data

---

- To: [netbsd-users%netbsd.org@localhost](mailto:netbsd-users%netbsd.org@localhost)
  - Subject: aligning control message ancillary data
  - From: Taylor R Campbell <[campbell@mumble.net](mailto:campbell@mumble.net)@localhost>
  - Date: Tue, 17 Jun 2008 16:41:00 -0400
- 

Hello! Last night while debugging an issue in stunnel, I found that NetBSD (perhaps specifically NetBSD/macppc) is much more finicky than the other operating systems I tried concerning alignment of control message ancillary data. Setting up a msghdr structure with the following idiom, in order to send a file descriptor over a Unix-domain socket using only the facilities provided in the SUSv3 and documented in the `recvmsg(3)` man page, causes bogus file descriptors to be received on the other end:

```
struct msghdr msg;
struct cmsghdr * cm_ptr;
struct {
    struct cmsghdr c_msghdr;
    int fd;
} control;

msg.msg_control = (void *) &control;
```

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- ▶ Read kernel code for the first time
- ▶ Just C code, guessed how syscalls are implemented
- ▶ Found bug in `cmsg(3)` API for fd passing
- ▶ Proposed fix, committed by `christos@`

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- ▶ ... not quite fixed until later; fd passing is hard

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- ▶ Spent July and August porting bwi(4) from OpenBSD/DragonflyBSD
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- ▶ ... didn't do a great job, not a wifi expert

# How to get started hacking NetBSD

Check out source tree (a few gigabytes):

- ▶ `cvs -d anoncvs@anoncvs.NetBSD.org:/cvsroot co -P src`
- ▶ `git clone https://github.com/NetBSD/src`
- ▶ `hg clone https://anongh.NetBSD.org/src`

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(use `./build.sh list-arch` to see all options)

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Build a release:

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```

- `-O ../obj` build products go here
  - `-U` unprivileged build (traditionally privileged in `/usr/src`)
  - `-u` update build, don't clean
- `-m alpha` build for DEC Alpha architecture  
(use `./build.sh list-arch` to see all options)
- `-N1` verbosity level 1
- `-j4` 4-way parallel build
- `release` build a NetBSD release  
(use `./build.sh help` to see all operations)

# What's in your NetBSD release build

- `../obj/tooldir.NetBSD-9.3-amd64`  
cross-compiler toolchain
- `../obj/releasedir/${MACHINE_ARCH}`  
release products, including distribution sets, kernels,  
and install/live media
- `../obj/destdir.${MACHINE}`  
staged NetBSD installation
- `../obj/usr.bin/find`  
build tree for find(1) from src/usr.bin/find
- `../obj/sys/arch/${MACHINE}/compile/GENERIC`  
build tree for GENERIC kernel, including netbsd  
kernel image (may vary on some ports)

## Other useful build.sh targets

`./build.sh help`

`./build.sh list-arch`

`./build.sh tools`

build just cross-compiler toolchain

`./build.sh distribution`

build just (tools and) userland but not kernels or release

`./build.sh sets`

build just distribution sets

`./build.sh modules`

build just kernel modules

# Build a kernel

1. `./build.sh [...] tools`
2. `./build.sh [...] kernel=GENERIC`
  - ▶ Note: For 64-bit Arm and 64-bit RISC-V, use `kernel=GENERIC64`, not `kernel=GENERIC`.
  - ▶ Some ports have various special-purpose kernels, not `GENERIC`, such as `evbppc TWRP1025`.

## Custom kernel config

- ▶ Local custom changes to GENERIC in `sys/arch/.../conf/GENERIC.local` (or `sys/arch/.../conf/GENERIC64.local`).
- ▶ Custom kernel config in `sys/arch/.../conf/MYKERNEL`.

Example `sys/arch/amd64/conf/DEBUG`:

```
include "arch/amd64/conf/GENERIC"  
  
options  DEBUG  
options  KERNHIST  
options  LOCKDEBUG  
options  UVMHIST
```

## Boot aarch64 in qemu

```
# Create a disk image.
mkdir ~/vm
cd ~/obj/releasedir/evbarm-aarch64/binary/gzimg
gunzip -c <arm64.img.gz >~/vm/disk.img

# Make it a sparse 10 GB image.
cd ~/vm
dd if=/dev/zero of=disk.img oseek=10g bs=1 count=1

# Make a symlink to the kernel.
KERNDIR=~/obj/sys/arch/evbarm/compile/GENERIC64
ln -sf $KERNDIR/netbsd.img .
```

## Start qemu-system-aarch64

```
qemu-system-aarch64 \  
-kernel netbsd.img \  
-append "root=dk1" \  
-M virt \  
-cpu cortex-a53 \  
-smp 2 \  
-m 1g \  
-drive if=none,file=disk.img,id=disk,format=raw \  
-device virtio-blk-device,drive=disk \  
-device virtio-rng-device \  
-nic user,model=virtio-net-pci \  
-nographic
```

## Updating kernel for non-aarch64

- ▶ Use `vnd(4)` and/or `rump_ffs(4)` to mount `disk.img`
- ▶ (Volunteer needed to make NetBSD support booting with `-kernel netbsd` under `qemu` on other architectures!)

## gdb on live kernel under qemu

- ▶ `$ qemu-system-aarch64 [...] -s [...]`
- ▶ `$ gdb netbsd.gdb`  
`(gdb) target remote localhost:1234`

## gdb on live kernel under qemu

- ▶ `$ qemu-system-aarch64 [...] -s [...]`
- ▶ `$ gdb netbsd.gdb`  
`(gdb) target remote localhost:1234`
- ▶ `qemu -s` is short for `-gdb tcp:1234`.

## `gdb` on live running kernel

```
# gdb netbsd.gdb  
(gdb) target kvm /dev/mem
```

## `gdb` and `crash(8)` on system core dumps

```
# gdb netbsd.gdb
(gdb) target kvm /var/crash/netbsd.n.core
```

```
# crash -M /var/crash/netbsd.n \
        -N /var/crash/netbsd.n.core
crash> bt
crash> ps
```

(see `ddb(4)` for more commands)

```
# dmesg -M /var/crash/netbsd.n \
        -N /var/crash/netbsd.n.core
```

# Verify system core dumps work!

Force the system to crash:

```
# sysctl -w debug.crashme_enable=1  
# sysctl -w debug.crashme.panic=1
```

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Many other crashme nodes:

- ▶ simulate panic

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# Verify system core dumps work!

Many other crashme nodes:

- ▶ simulate panic
- ▶ enter ddb directly
- ▶ recursively lock mutex(9)
- ▶ enter infinite loop with interrupts blocked
- ▶ launch golang, a well-known alternative test suite for NetBSD

## Run ATF tests

```
# cd /usr/tests  
# atf-run | atf-report
```

# Run ATF tests unprivileged

```
$ cd /usr/tests  
$ atf-run | atf-report
```

- ▶ Not all ATF tests can run unprivileged
- ▶ Those that can avoid changing system configuration

## Run ATF tests and save output

```
# cd /usr/tests
# atf-run | tee /var/tmp/atf-run.out \
    atf-report | tee /var/tmp/atf-report.out
```

## Run ATF tests in a chroot

```
# chroot ~/obj/destdir.amd64
chroot# cd /dev && sh MAKEDEV all
chroot# mount -t ptyfs ptyfs /dev/pts
chroot# mount -t tmpfs tmpfs /tmp
chroot# cd /usr/tests
chroot# atf-run | atf-report
```

Requires kernel at least as new as the chroot userland.  
Very handy for testing pullups to release branches!

## Developing one program/library at a time

```
$ cd ~/src/usr.bin/find
$ $TOOLDIR/bin/nbmake-$MACHINE_ARCH -j4 dependall
$ $TOOLDIR/bin/nbmake-$MACHINE_ARCH -j4 install
```

- ▶ Test again straight from the chroot!
- ▶ (For libraries: works only for dynamic libraries; static libraries require rebuilding downstream users.)
- ▶ One makefile per program/library, usually short.
- ▶ See `src/share/mk/bsd.README` for more information.

## Changing an include file

```
$ cd ~/src/include
```

```
$ $TOOLDIR/bin/nbmake-$MACHINE_ARCH -j4 includes
```

# Device drivers

- ▶ Autoconf drivers: represent hardware devices NetBSD can detect and handle
- ▶ devsw entries: /dev interfaces between userland and kernel

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- ▶ Autoconf drivers: represent hardware devices NetBSD can detect and handle
- ▶ devsw entries: /dev interfaces between userland and kernel
- ▶ Sometimes correspond

# Anatomy of an autoconf driver

Driver for hardware that can be detected by bus enumeration

```
struct foodev_softc {
    device_t      sc_self;
    kmutex_t      sc_lock;
    ...
};

CFATTACH_DECL2_NEW(foodev, sizeof(struct foodev_softc),
    foodev_match, foodev_attach, foodev_detach,
    NULL, NULL, NULL);
```

(Some day we'll switch to C99 designated initializers!)

## Anatomy of an autoconf driver

```
static int
foo_match(device_t self, cfmatch_t match, void *aux)
{
    const struct pci_attach_args *pa = aux;
    ...
}
```

```
static int
foo_attach(device_t parent, device_t self, void *aux)
{ ... }
```

```
static int
foo_detach(device_t self, int flags)
{ ... }
```

# Anatomy of an autoconf driver

- `foo_match` Can this driver handle this device? If so, with what priority versus other drivers that can?
- `foo_attach`
- ▶ Allocate resources for the device's driver state.
  - ▶ Expose the device to any other kernel interfaces.
  - ▶ Scan for children if any.
- `foo_detach` Device has been removed. Disconnect any users in other kernel interfaces and free resources.

See <https://www.NetBSD.org/gallery/presentations/riastradh/eurobsdcon2022/ependetach.pdf> for more on tricky issues with detach!



## Anatomy of a /dev character special

Interface between userland and kernel identified by major and minor number stored in character special on disk.

```
const struct cdevsw foo_cdevsw = {
    .d_open = foo_open,
    .d_close = foo_close,
    .d_read = foo_read,
    .d_write = foo_write,
    ...
    .d_cfdriver = &foodev_cd,
    .d_devtounit = dev_minor_unit,
    ...
};
```

(Don't forget to add to src/sys/conf/majors, or the appropriate machine-dependent majors list, and etc/MAKEDEV!)

# Cloning devices

- ▶ Traditional `/dev` nodes correspond to a single hardware device with per-device state.
  - ▶ `/dev/wd0` corresponds to first ATA hard drive
  - ▶ `/dev/sd0` corresponds to first SCSI hard drive
  - ▶ `/dev/ttyU0` corresponds to first USB serial port
- ▶ **Cloning devices** have per-open state.
  - ▶ `/dev/audio` virtual mixed-audio interface
  - ▶ `/dev/dri/card0` graphics rendering interface
  - ▶ `/dev/vhci` USB virtual host controller interface

## Cloning devices

```
const struct cdevsw foo_cdevsw = {
    .d_open = foo_open,
    .d_close = noclose,
    .d_read = noread,
    .d_write = nowrite,
    ...
};

static const struct fileops foo_fileops = {
    .fo_name = "foo",
    .fo_read = foo_read,
    .fo_write = foo_write,
    ...
};
```

## Cloning devices

```
static int
foo_open(dev_t d, int flags, int fmt, struct lwp *l)
{
    struct file *fp;
    int fd;
    int error;

    error = fd_allocfile(&fp, &fd);
    if (error)
        return error;
    ...
    error = fd_clone(fp, fd, flags,
        &foo_fileops, privatedata);
    KASSERT(error == EMOVEFD);
    return error;
}
```

## Access to device registers: bus\_space(9)

```
bus_space_tag_t bst;
bus_space_handle_t bsh;
uint32_t ctl;
int error;

bst = args->bst;
error = bus_space_map(bst, args->addr, args->size, 0,
    &bsh);
if (error)
    goto fail;

ctl = bus_space_read_4(bst, bsh, FOO_CTL);
if (ctl & FOO_BROKEN)
    goto broken;
ctl |= FOO_ENABLED;
bus_space_write_4(bst, bsh, FOO_CTL, foo);
```

## Handy macros for device register fields

```
#include <sys/cdefs.h>

#define RK_V1CRYPTO_TRNG_CTRL    0x0200 /* TRNG Control */
#define RK_V1CRYPTO_TRNG_CTRL_OSC_ENABLE  __BIT(16)
#define RK_V1CRYPTO_TRNG_CTRL_CYCLES    __BITS(15,0)
...
ctrl = RK_V1CRYPTO_TRNG_CTRL_OSC_ENABLE;
ctrl |= __SHIFTIN(100, RK_V1CRYPTO_TRNG_CTRL_CYCLES);
RKC_WRITE(sc, RK_V1CRYPTO_TRNG_CTRL, ctrl);
```

# Exposing memory to devices: bus\_dma(9)

DMA: Direct memory access

- ▶ Allocate buffers at addresses that are safe for DMA
- ▶ Map buffers to bus addresses with IOMMU
  - ▶ E.g., map user buffer from write(2) so ethernet device can copy it out to the network
- ▶ Handle bouncing if buffers can't be mapped directly

# Testing kernel components with Rump

- ▶ Rump runs unmodified kernel components and device drivers in userland processes, by setting up state just like a kernel
- ▶ NetBSD test suite uses Rump extensively to test kernel components, such as file systems
- ▶ Edit, compile, test kernel components from userland:
  - ▶ run `nbmake-$MACHINE dependall/install` from `src/sys/rump` (or selective subdirectories)
  - ▶ redo `atf-run/report` from `chroot`

Now get hacking NetBSD!

Questions?